In attendance:

Dominic

James

Saad

John

Not in attendance:

Emre

Discussed

New Arm length

Gripper design

Electromagnet was decided

Project management base

What we need to do:

All – Each do a stakeholder analysis

Dom – Responsibility matrix, verification plan, put measurements of the box on GitHub

James – Make PCB, make base

Saad – Adjust kinematics for a raised robot

John – CAD model of the base

Emre – Financial plan (Profit and Loss), Health and safety documentation